

## CHQ x2xx

# Precision CAMAC High Voltage Supply CHQ HIGH PRECISION series CAMAC - Interface

## Operators Manual

### Contents:

1. General information

2. Technical data

3. CHQ Description

4. Front panel

5. Handling

6. CAMAC Interface

Appendix A: Block diagram

Appendix B: Rotary switch locations

### Attention!

-It is not allowed to use the unit if the covers have been removed.

-We decline all responsibility for damages and injuries caused by an improper use of the module. It is highly recommended to read the operators manual before any kind of operation.

### Note

The information in this manual is subject to change without notice. We take no responsibility whatsoever for any error in the document. We reserve the right to make changes in the product design without reservation and without notification to the users.

Filename CHQ\_x2x\_01\_eng; version 3.10 as of 2012-03-06

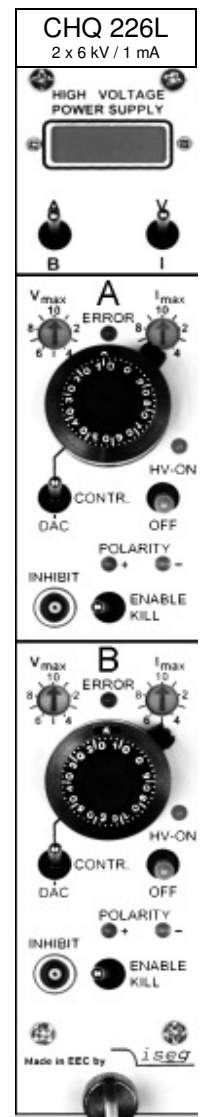
## 1. General information

The CHQ x2xx are single- or dual-channel high voltage supplies with higher stability and improved capabilities compared to the CHQ STANDARD series in a CAMAC chassis. The units are 2 slot wide, and offer manual control via the front panel and operation via the CAMAC interface. The operation via the interface features an increased functionality and HIGH RESOLUTION control parameters and measurement values.

The high voltage supplies provide a high precision output voltage together with very low ripple and noise, even under full load. Separate hardware switches allow to put voltage and current limits in 10%-steps. The EXINHIBIT input protects sensitive devices. Additionally, a maximum output current per channel can be specified via the interface. The high voltage source is protected against overload and short circuit. The output polarity can be switched over.

## 2. Technical Data

| Single-channel HV-PS                      | CHQ  | 122M  | 123M                     | 124M               | 125M                     | 126L   |
|---|--|---|--------------------------|--------------------|--------------------------|--------|
| Dual-channel HV-PS                        | CHQ  | 222M  | 223M                     | 224M               | 225M                     | 226L   |
| Output voltage $V_O$ [kV]                 |  | 0 to 2  | 0 to 3                   | 0 to 4             | 0 to 5                   | 0 to 6 |
| Output current per channel $I_{OUT}$ [mA] |  | 0 to 6  | 0 to 4                   | 0 to 3             | 0 to 2                   | 0 to 1 |
| Ripple                                    |  | max. 2 mV <sub>p-p</sub>  |                          |                    | max. 5 mV <sub>p-p</sub> |        |
| Stability                                 | $\frac{\Delta V_O}{\Delta V_{INPUT}}$ (no load / load) | $< 5 * 10^{-5}$   |                          |                    |                          |        |
|   | $\frac{\Delta V_O}{\Delta V_{INPUT}}$                  | $< 3 * 10^{-5}$   |                          |                    |                          |        |
| Temperature coefficient                   |  | $< 3 * 10^{-5} / K$   |                          |                    |                          |        |
| Resolution of usable voltage setting      | via Interface  | 100 mV, with <b>Option VHR</b> : 30 mV ( $V_{Omax} \leq 4kV$ )<br>80 mV ( $V_{Omax} > 4kV$ )  |                          |                    |                          |        |
|   | manual   | 1 V   |                          |                    |                          |        |
| Resolution of voltage measurement         | via Interface  | 100 mV, with <b>option VHR</b> : 10 mV ( $V_{Omax} \leq 4kV$ )  |                          |                    |                          |        |
|   | Display  | 1 V   |                          |                    |                          |        |
| Resolution of current measurement         | range (MR <sub>I</sub> )                               | with <b>option:</b>   | <b>2MA</b>               | <b>2MA and 0n1</b> |                          |        |
|   |  | $I=1: I_{OUTmax}$   | $I=2: 100 \mu A$         | $I=2: 10 \mu A$    |                          |        |
|   | via Interface  | 100 nA  | 1 nA                     | 100 pA             |                          |        |
|   | Display  | 1 $\mu A$   | 10 nA                    | 1 nA               |                          |        |
| Accuracy current measurement              |  | $\pm (0,1\% * I_O + 0,05\% * MR_I)$ for one year  |                          |                    |                          |        |
| Accuracy voltage measurement              |  | $\pm (0,05\% * V_O + 0,02\% * V_{OUTmax})$ for one year   |                          |                    |                          |        |
| Voltage control                           | CONTROL switch in:                                     | upper position:   | 10 - turn potentiometer  |                    |                          |        |
|   |  | lower position (DAC):   | control via interface    |                    |                          |        |
| Rate of change of output voltage          |  | hardware ramp:  | 500 V/s (on HV-ON/ -OFF) |                    |                          |        |
|   |  | software ramp:  | 2 ... 255 V/s            |                    |                          |        |
| Protection                                |  | <ul style="list-style-type: none"> <li>- separate current and voltage limit (hardware, rotary switch in 10%-steps)</li> <li>- EXINHIBIT (ext. signal, TTL-level, Low = active)</li> <li>- programmable current trip (software)</li> </ul> |                          |                    |                          |        |
| Power requirements $V_{INPUT}$            |  | $\pm 24 V$ (< 800 mA, single channel < 400 mA),<br>$\pm 6 V$ (< 100 mA)   |                          |                    |                          |        |
| Case                                      |  | CAMAC-Standard module: CAMAC #2   |                          |                    |                          |        |
| Connectors                                |  | CAMAC: CAMAC interface connector,<br>EXINHIBIT: 1-pin Lemo-hub,<br>HV connector: SHV connector on the rear side   |                          |                    |                          |        |
| Operating temperature                     |  | 0 ... +50 °C  |                          |                    |                          |        |
| Storage temperature                       |  | -20 ... +60 °C  |                          |                    |                          |        |



Implemented **options** are labeled on the rear panel of the unit.

### 3. CHQ Description

The functional principle is described in the block diagram, Appendix A.

#### High voltage supply

For the high voltage generation a patented highly efficient resonance converter circuit is used, which provides a sinusoidal voltage with low harmonics for the HV-transformer. For the high voltage rectification high speed HV-diodes are used. A high-voltage switch, connected to the rectifier allows the selection of the polarity. The consecutive active HV-filter damps the residual ripple and ensures low ripple and noise values as well as the stability of the output voltage. A precision voltage divider is integrated in the HV-filter to provide a feedback voltage for the output voltage control, an additional voltage divider supplies the signal for the maximum voltage monitoring. A precision control amplifier compares the feedback voltage with the set value given by the DAC (remote control) or the potentiometer (manual control). Signals for the control of the resonance converter and the stabilizer circuit are derived from the result of the comparison. The two-stage layout of the control circuit results in an output voltage, stabilized with very high precision to the set point.

Separate security circuits prevent exceeding the front-panel switch settings for the current  $I_{\max}$  and voltage  $V_{\max}$  limits. A monitoring circuit prevents malfunction caused by low supply voltage.

The internal error detection logic evaluates the corresponding error signals and the external EXINHIBIT signal and impacts the output voltage according to the setup. In addition this allows the detection of short over currents due to single flashovers.

#### Digital control unit

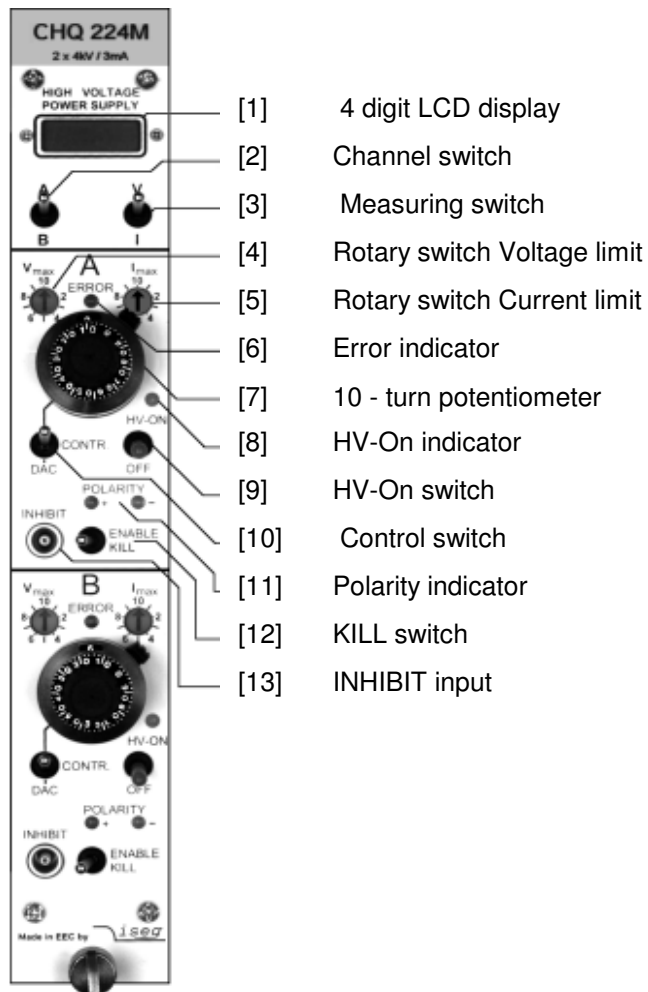
A micro controller handles the internal control, evaluation and calibration functions of both channels. The actual voltages and currents are read cyclically by an ADC with a connected multiplexer. The readings are processed and displayed on the 4 digit LCD. The current and voltage hardware limits are retrieved cyclically several times per second. A reference voltage source provides a precise voltage reference for the ADC and the control voltage for the manual operation mode of the unit.

In the computer controlled mode the set values for the corresponding channels are generated by a 18-Bit DAC.

#### Filter

A special feature of the unit is a tuned filtering concept, which prevents perturbation of the unit by external electromagnetic radiation, as well as the emittance of interferences by the module. A filtering network for the supply voltages is located next to their connectors, the converter circuits of the individual channels are protected by additional filters. The high-voltage filters are housed in individual metal enclosures to shield even minimal interference radiation.

## 4. Front panel



## 5. Handling

By connecting the CAMAC-connector on the backside the unit is set into the operating state.

Before the unit is powered the desired output polarity must be selected by the rotary switch on the cover side (see appendix B). The chosen polarity is displayed by a LED on the front panel [11] and a sign on the LCD [1].

**Attention!** It is not allowed to change the polarity under power!

If the switch setting is undefined (not at one of the end positions) high voltage cannot be switched on.

High voltage output is switched on with the HV-ON switch [9] at the front panel. The viability is signaled by the yellow LED [8].

**Attention!** If the CONTROL switch [10] is in upper position (manual control), high voltage is generated at the HV-output on the rear side, started with a ramp speed of 500 V/s (hardware ramp) to the set voltage given by the 10-turn potentiometer [7].

This is also the case, if CAMAC control is switched over to manual control while operating.

If the CONTROL switch [10] is in lower position (DAC), high voltage will be activated only after receiving corresponding CAMAC commands.

The LCD [1] displays the output voltage in [V] or the output current in [ $\mu$ A], depending on the position of the Measuring switch [3].

For two channel units the Channel switch [2] selects whether channel (A) or channel (B) is displayed. For single channel modules with the option CHQ 02 (manual current measurement range switch) the current measurement range is selected at this position.

In the manual control mode the output voltage can be set via 10-turn potentiometer [7] in a range from 0 to the maximum voltage.

If the CONTROL switch [10] is switched over to remote control, the DAC takes over the last set output voltage of the manual control. The output voltage can be changed remotely with a programmable ramp speed (software ramp) from 2 to 255 V/s in a range from 0 to the maximum voltage.

The maximum output current for each channel (current trip) can be set via the remote interface in units of the resolution of the upper measurement range. If the output current exceeds the programmable limit, the output voltage will be shut off permanently by the software. A recovery of the voltage is possible after "Read LAM-Status" and then "Start voltage change" via the interface.

The maximum output voltage and current can be selected in 10%-steps with the rotary switches  $V_{max}$  [4] and  $I_{max}$  [5] (switch dialed to 10 corresponds to 100%) independently of programmable current trip. The red error LED on the front panel [6] signals if the output voltage or current approaches the limits.

The KILL switch [12] specifies the response on exceeding limits or on the external protection signal (EXINHIBIT) at the INHIBIT input [13] as follows:

Switch to the right position: (ENABLE KILL) When exceeding  $V_{max}$ ,  $I_{max}$  or in the presence of an EXINHIBIT signal (Low=active) the output voltage will be shut off permanently without ramp. The output voltage is only restored after switching HV-ON [9] or KILL [12] or "Read LAM-Status" and then "Start voltage change" when using DAC control.

Note: If a capacitance is effective at the HV-output or when using a high voltage ramp speed (hardware ramp) under high loads, then the KILL function may be triggered by the capacitor charging currents. In this case smaller output voltage change rates (software ramp) should be used or ENABLE KILL should only be selected once the set voltage is reached at the output.

Switch to the left position: (DISABLE KILL) The output voltage is limited to  $V_{max}$ , the output current to  $I_{max}$  respectively; INHIBIT shuts the output voltage off without ramp, the previous voltage setting will be restored with hard- or software ramp once EXINHIBIT is no longer being present.

## 6. Operation under CAMAC control

The following functionality is provided for the operation of the high voltage units via the CAMAC interface.

### CAMAC control mode

- Write functions: set voltage; ramp speed; maximal output current (current trip)
- Switch functions: output voltage = set voltage, output voltage = 0
- Read functions: set voltage; actual output voltage; ramp speed; actual output current; current trip; hardware limits current and voltage; status
- Alarm function: LAM

Front panel switches have priority over software control.

### Manual control mode

While the unit is operated in manual control mode, CAMAC read cycles are interpreted only. Commands are accepted, but do not result in a change of the output voltage.

## CAMAC commands

The data are BCD coded for voltages, currents, current trips and ramps as follow:

|                        | (W)RITE ( ... Input data)   | (R)EAD ( ... Output data)          |
|------------------------|-----------------------------|------------------------------------|
| Voltage                | u u u u , u x in [V]        | u u u u , u 0 in [V]               |
| with <b>option VHR</b> | u u u u , u u in [V]        | u u u u , u u in [V]               |
| Current                |                             | i i i i i f in [ $10^{(-12+f)}$ A] |
| Current trip           | i i i i , i x in [ $\mu$ A] | i i i i , i x in [ $\mu$ A]        |
| Ramp                   | 0 v v v , 0 0 in [V/s]      | 0 v v v , 0 0 in [V/s]             |

Z S(2)          general reset

| N AF       | Type | Description                                    | Remark   |
|------------|------|--|--|
| A(0)F(0)   | R    | Set voltage channel A                          |  |
| A(1)F(0)   | R    | Set voltage channel B                          |  |
| A(2)F(0)   | R    | Ramp channel A                                 | 2 ... 255 V/s  |
| A(3)F(0)   | R    | Ramp channel B                                 | 2 ... 255 V/s  |
| A(4)F(0)   | R    | Measured voltage channel A                     |  |
| A(5)F(0)   | R    | Measured voltage channel B                     |  |
| A(6)F(0)   | R    | Measured current channel A                     |  |
| A(7)F(0)   | R    | Measured current channel B                     |  |
| A(8)F(0)   | R    | Limits channel A                               | ⇒ Bit assignments  |
| A(9)F(0)   | R    | Limits channel B                               | ⇒ Bit assignments  |
| A(10)F(0)  | R    | Current trip channel A                         | with the resolution of current measurement,<br>for I = 0 not current trip    |
| A(11)F(0)  | R    | Current trip channel B                         |  |
| A(0)F(1)   | R    | Module status                                  | ⇒ Status register  |
| A(12)F(1)  | R    | LAM-Status                                     | ⇒ LAM register   |
| A(13)F(1)  | R    | LAM-Mask                                       |  |
| A(14)F(1)  | R    | LAM-Request                                    |  |
| A(15)F(1)  | R    | Module identifier                              | ⇒ Bit assignments  |
| A(0)F(16)  | W    | Set voltage channel A                          |  |
| A(1)F(16)  | W    | Set voltage channel B                          |  |
| A(2)F(16)  | W    | Ramp channel A                                 | 2 ... 255 V/s  |
| A(3)F(16)  | W    | Ramp channel B                                 | 2 ... 255 V/s  |
| A(4)F(16)  | W    | Set voltage and start voltage change channel A | Set voltage will overwrite A(0)F(16),<br>without precision calibration       |
| A(5)F(16)  | W    | Set voltage and start voltage change channel B | Set voltage will overwrite A(1)F(16),<br>without precision calibration       |
| A(10)F(16) | W    | Current trip channel A                         | with the resolution of current measurement,<br>for I = 0 not current trip    |
| A(11)F(16) | W    | Current trip channel B                         |  |
| A(13)F(17) | W    | LAM-Mask                                       |  |
| A(0)F(25)  | 0    | Start voltage change channel A                 | Set voltage according to A(0)F(16),<br>with continuous precision calibration |
| A(1)F(25)  | 0    | Start voltage change channel B                 | Set voltage according to A(1)F(16),<br>with continuous precision calibration |
| A(15)F(8)  | 0    | Test LAM                                       | Q=LAM  |

### Status register

| Channel  | Bit | Name     | Description                         | 0                 | 1                   |
|----------|-----|----------|-------------------------------------|-------------------|---------------------|
| <b>B</b> | R16 | ERROR_2  | Error in Channel B                  | channel ok        | error               |
|          | R15 | STATV_2  | Status $V_{out}$                    | $V_{out}$ stable  | $V_{out}$ in change |
|          | R14 | TRENDV_2 | Ramp up/down $V_{out}$              | $V_{out}$ falling | $V_{out}$ rising    |
|          | R13 | KILL_2   | KILL switch setting                 | disabled          | enabled             |
|          | R12 | ON_OFF_2 | HV-ON/OFF switch setting            | on                | off                 |
|          | R11 | POL_2    | Polarity Output voltage             | negative          | positive            |
|          | R10 | IN_EX_2  | CONTROL switch setting              | DAC               | manual              |
|          | R9  | VZ_2     | Output voltage Channel B equal to 0 | $V_{out} <> 0$    | $V_{out} = 0$       |
| <b>A</b> | R8  | ERROR_1  | Error in Channel A                  | channel ok        | error               |
|          | R7  | STATV_1  | Status $V_{out}$                    | $V_{out}$ stable  | $V_{out}$ in change |
|          | R6  | TRENDV_1 | Ramp up/down $V_{out}$              | $V_{out}$ falling | $V_{out}$ rising    |
|          | R5  | KILL_1   | KILL switch setting                 | disabled          | enabled             |
|          | R4  | ON_OFF_1 | HV-ON/OFF switch setting            | on                | off                 |
|          | R3  | POL_1    | Polarity Output voltage             | negative          | positive            |
|          | R2  | IN_EX_1  | CONTROL switch setting              | DAC               | manual              |
|          | R1  | VZ_1     | Output voltage Channel A equal to 0 | $V_{out} <> 0$    | $V_{out} = 0$       |

This register is representing the general status of the CHQ.

“Error“ is a combination with a logic OR of \_REG2ER\_, \_REG1ER\_, \_EXTINH\_, \_RANGE\_ and \_ILIM\_ from the LAM register.

“ $V_{out}=0$ “ is true when DAC output = 0 AND actual voltage < 5 V.

### LAM register

| Channel  | Bit | Name            | Description for bit = 1                                  | Remark                     |
|----------|-----|-----------------|--|----------------------------|
| <b>B</b> | R16 | LAM_REG2ER_2    | Quality of output voltage channel B not given at present |                            |
|          | R15 | LAM_REG1ER_2    | $V_{max}$ or $I_{max}$ is / was exceeded                 |                            |
|          | R14 | LAM_EXTINH_2    | EXINHIBIT signal was / is active (0 = inactive)          |                            |
|          | R13 | LAM_RANGE_2     | Set voltage channel B exceeds voltage limit              | $W(A1F16) > V_{max}$       |
|          | R12 | LAM_KEY_CHANGED | Front panel switch was changed channel B                 | ON_OFF_2, IN_EXT_2, KILL_2 |
|          | R11 | LAM_EOP_2       | $V_{out}$ channel B according to set voltage             | end of process_2           |
|          | R10 | LAM_ILIM_2      | Current trip was active channel B                        | $I_{out} > I_{max}$ trip   |
| <b>A</b> | R8  | LAM_REG2ER_1    | Quality of output voltage channel A not given at present |                            |
|          | R7  | LAM_REG1ER_1    | $V_{max}$ or $I_{max}$ is / was exceeded                 |                            |
|          | R6  | LAM_EXTINH_1    | EXINHIBIT signal was / is active (0 = inactive)          |                            |
|          | R5  | LAM_RANGE_1     | Set voltage channel A exceeds voltage limit              | $W(A0F16) > V_{max}$       |
|          | R4  | LAM_KEY_CHANGED | Front panel switch was changed channel A                 | ON_OFF_1, IN_EXT_1, KILL_1 |
|          | R3  | LAM_EOP_1       | $V_{out}$ channel A according to set voltage             | end of process_1           |
|          | R2  | LAM_ILIM_1      | Current trip was active channel A                        | $I_{out} > I_{max}$ trip   |

The individual bits are set on the occurrence of the event. A general clear is performed after readout.

If the Output voltage was permanently switched off by exceeding  $V_{max}$  or  $I_{max}$  (ENABLE KILL resp. Current trip), or EXINHIBIT respectively, the error bits (REG1ER\_, EXTINH\_, ILIM\_) have to be reset by reading “ LAM register “ before an output voltage can be set again.

## Bit assignments

### A(15)F(1)          Module identifier

|             |           |   |
|-------------|-----------|---|
| R24 ... R01 | BCD coded | 3 digit: firmware version<br>3 digit: last three digit of serial number |
|-------------|-----------|---|

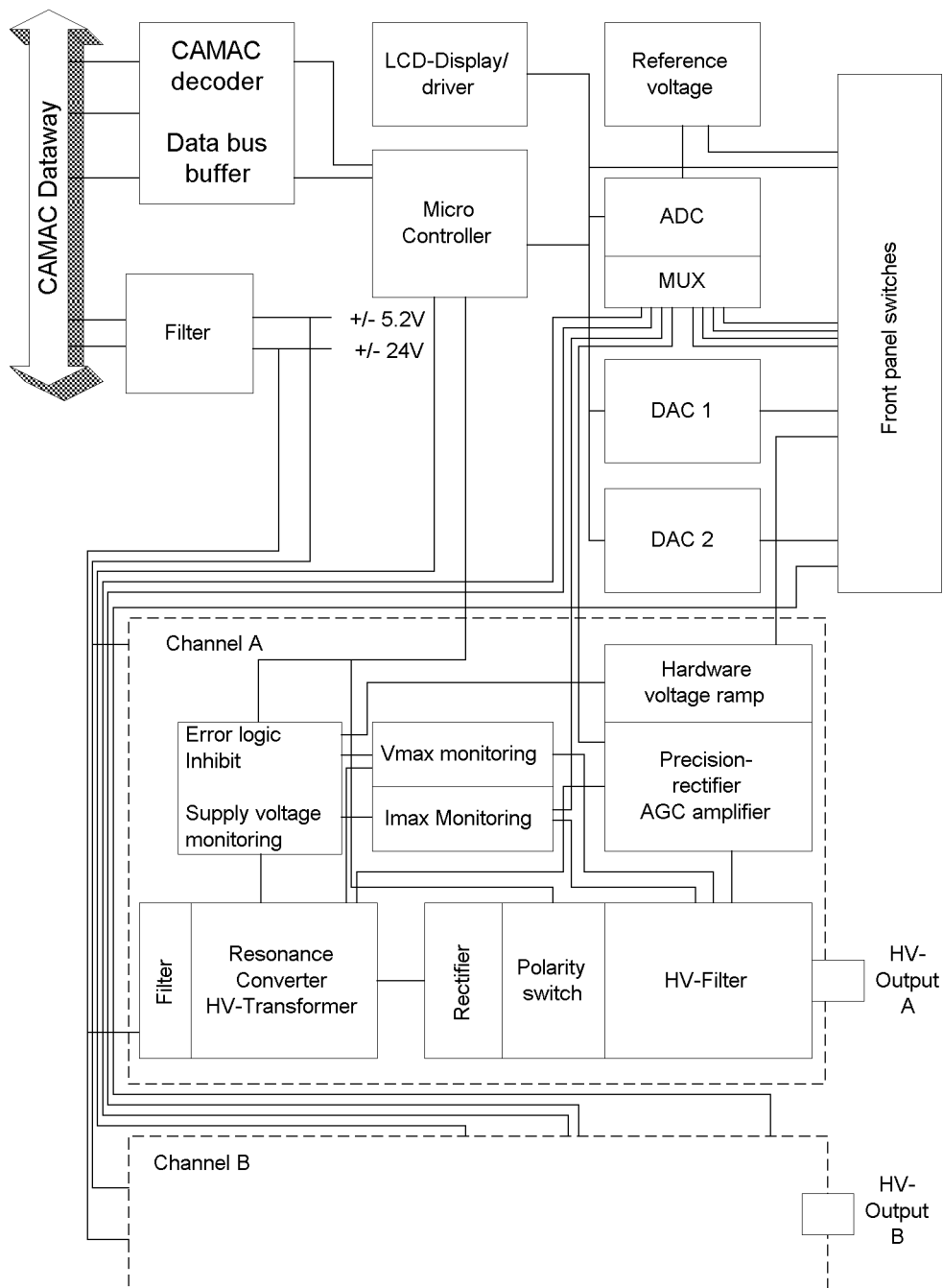
### A(8)F(0) / A(9)F(0)   Limits channel A / B

|             |           |             |           |                        |
|-------------|-----------|-------------|-----------|------------------------|
| R24 ... R17 | mantissa, | R16 ... R13 | exponent: | Maximal voltage in [V] |
| R12 ... R05 | mantissa, | R04 ... R01 | exponent: | Maximal current in [A] |

## Command execution

When a reading command is carried out for the first time, the respective data has to be made available first, so that there no valid data in this cycle (Q=0). Valid data can be collected with the same command after approx. 200µs (Q=1). After reading measured data (voltage or current), this data will be updated only after approx. 400ms (ADC converting time). Until this the last measured data is read.

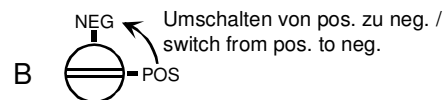
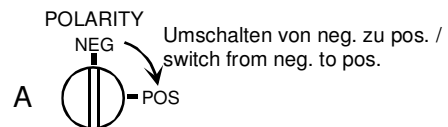




**Appendix A :** CHQ block diagram

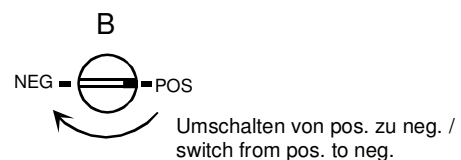
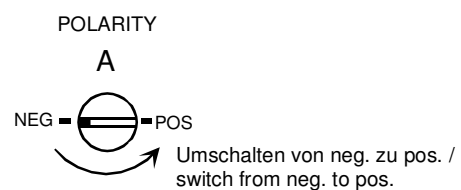
CHQ mit Voutmax bis zu 5kV /

CHQ with Voutmax up to 5kV



CHQ mit Voutmax > 5kV /

CHQ with Voutmax > 5kV



**Appendix B:**

CHQ side coffer,

Polarity rotary switch

eg.: channel A ⇒ polarity negative  
channel B ⇒ polarity positive